# STRAWBERRY



[] /strawberrydevelopers
[] /strawberry\_app

For more visit:

Strawberrydevelopers.weebly.com

## **PIN DIAGRAM**

Richa Upadhyay Prabhu

NMIMS's MPSTME

richa.upadhyay@nmims.edu

January 19, 2016

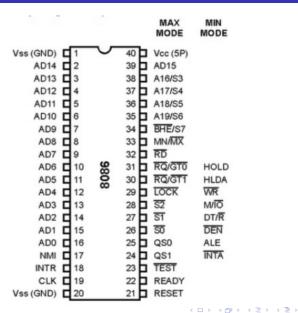
Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

January 19, 2016 1 / 51

Image: Image:

# Pin Diagram of 8086

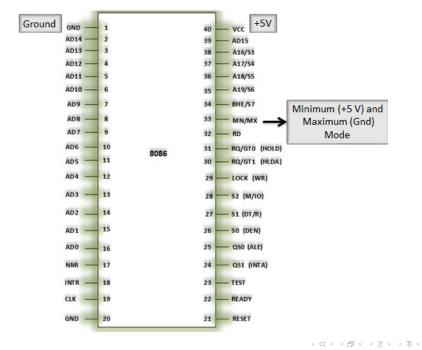


Richa Upadhyay Prabhu (MPSTME)

3

8086 can operate in two modes :

- Minimum Mode : unique processor system with a single 8086
- Maximum Mode : multiprocessor system with more than one 8086



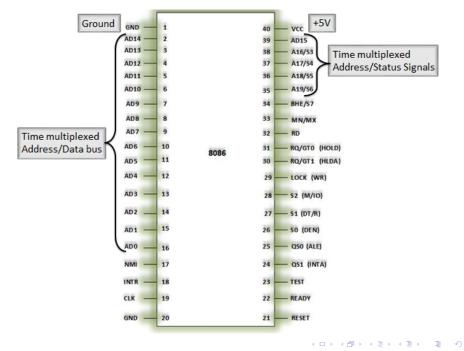
э

#### Minimum mode

- Pin 33 (MN/MX) connect to +5V
- Pin 24-31 are used as memory and I/O control signal
- The control signals are generated internally by the 8086/88

#### Maximum mode

- Pin 33 (MN/MX) connect to Ground
- Some control signals are generated externally by the 8288 bus controller chip
- Max mode is used when math processor is used.



January 19, 2016 6 / 51

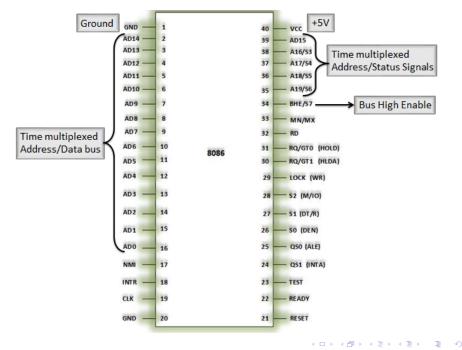
#### $AD_{15} - AD0$ : Address Data Bus

- 16-bit multiplexed address and data bus
- During the 1st clock cycle  $AD_0 AD_{15}$  are the low order 16-Bit address
- The 8086 has a total of 20 address line ,the upper 4 lines are multiplexed with the state signal that is A<sub>16</sub>/S<sub>3</sub>, A<sub>17</sub>/S<sub>4</sub>, A<sub>18</sub>/S<sub>5</sub>, A<sub>19</sub>/S<sub>6</sub>.
- During the first clock period the entire 20-bit address is available on these line
- In the next cycle,  $AD_{15} AD_0$  contain the 16 bit data and S3,S4,S5,S6 become the status line

 $S_3$  and  $S_4$  are decoded as follows

- 00 extra segment
- 01 stack segment
- 10 code or no segment
- 11 data segment

After the first clock cycle of an instruction execution, the  $A_{17}/S_4$  and  $A_{16}/S_3$  pins specify which segment register generates the segment portion of the 8086 address.

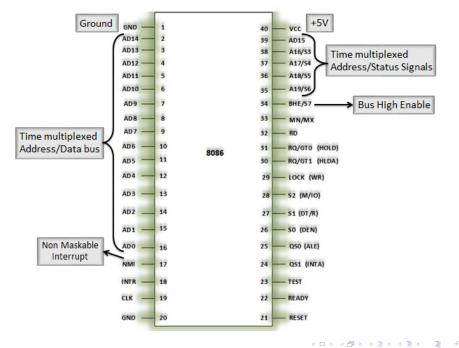


January 19, 2016 9 / 51

 $BHE/S_7$ : is used as bus high enable during the 1st clock cycle of an instruction execution

- Used to enable data on the most significant half of data bus
- or can say used to distinguish between the low byte and the high byte of the data for the 16-bit external data bus of 8086
- BHE is Low during T1 state of read, write and interrupt acknowledge cycles when a byte is to be transferred on the high portion of the bus.

BHE	AD0		
0	0	16-bit	D0-D15
0	1	8-bit	Upper half, D8-D15
1	0	8-bit	Lower half, D0-D7
1	1		Data Bus Idle

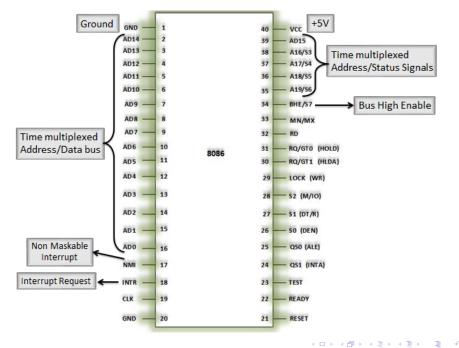


8080 Microprocessor

January 19, 2016 11 / 51

NMI : Non Maskable Interrupt; An edge triggered input, causes a type-2 interrupt.

- A subroutine is vectored to via the interrupt vector look up table located in system memory.
- NMI is not maskable internally by software.
- A transition from a LOW to HIGH on this pin initiates the interrupt at the end of the current instruction.
- This input is internally synchronized.

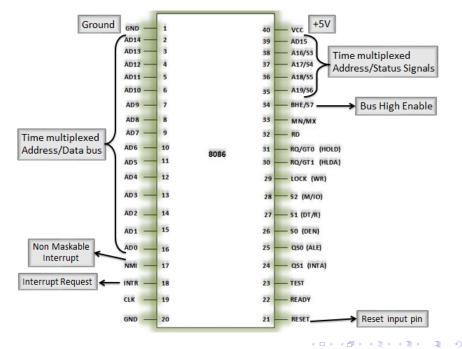


8080 Microprocessor

January 19, 2016 <u>13 / 51</u>

INTR (Interrupt Request)

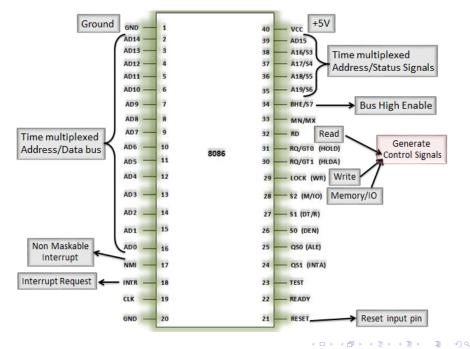
- An active-high level-triggered input signal to the processor
- Sampled in the last clock cycle of each instruction
- In IBM PC, this is connected to the 8259 Interrupt controller



January 19, 2016 15 / 51

RESET : causes the processor to immediately terminate its present activity

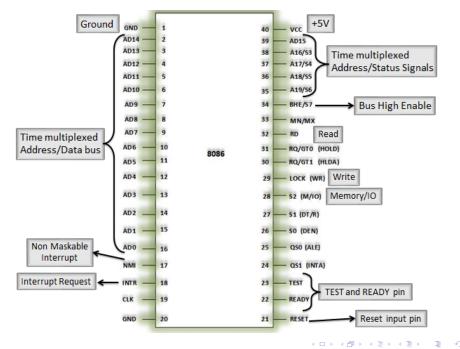
- Active high signal came from 8284
- Force the processor to stop any activities and to discard everything
- The signal must be active high for at least four clock cycles,
- Data after reset: CS: FFFFH, IP: 0000H, DS ES SS: 0000H Flags: Cleared, Queue: Empty



January 19, 2016 17 / 51

## using RD, WR and IO/M pins

WR	IO/M	Signal
1	0	MEMR
0	0	MEMW
1	1	IOR
0	1	IOW
0	x	Never happens
	WR 1 0 1 0 0	WR         IO/M           1         0           0         0           1         1           0         1           0         1           0         1           0         1           0         1           0         x



8080 Microprocessor

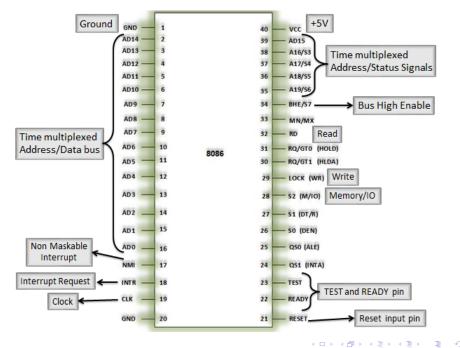
January 19, 2016 19 / 51

#### TEST

- TEST pin is examined by the "WAIT" instruction.
- If the TEST pin is Low, execution continues. Otherwise the processor waits in an "idle" state.
- This input is synchronized internally during each clock cycle on the leading edge of CLK.

READY

- $\bullet\,$  is the acknowledgement from the addressed memory or I/O device that it has completed the data transfer.
- The READY signal from memory or I/O is synchronized by the 8284 clock generator to form READY.
- This signal is active HIGH.

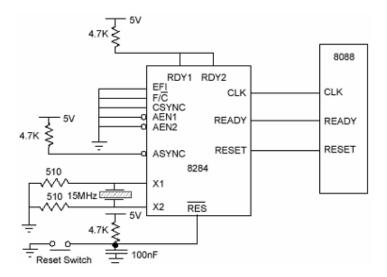


8080 Microprocessor

January 19, 2016 21 / 51

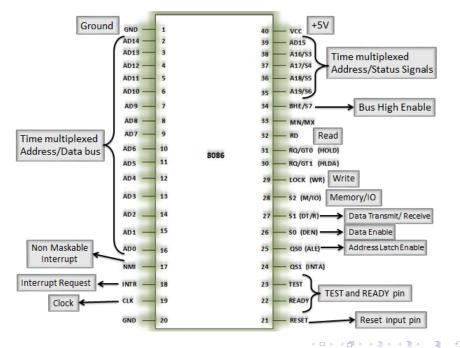
## CLOCK (heart beat of CPU)

- Clock provides the basic timing for the processor and bus controller.
- It is asymmetric with 33 percent duty cycle to provide optimized internal timing
- Minimum frequency of 5 MHz is required
- 8284 clock generator chip must be connected to the 8086 clock pin, since it does not have on chip clock generator
- The crystal connected to 8284 must have a frequency 3 times the 8086 internal frequency



2

イロト イヨト イヨト イヨト



8080 Microprocessor

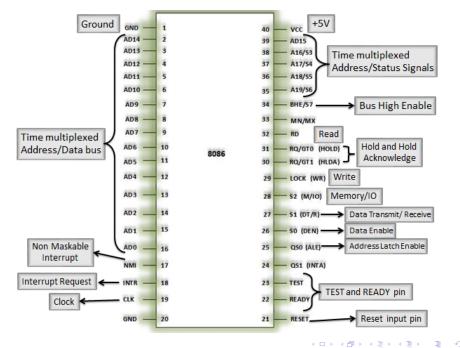
January 19, 2016 24 / 51

#### ALE : Address Latch Enable

ALE is provided by the processor to latch the address into the 8282/8283 address latch. It is an active high pulse during T1 of any bus cycle.

DT/ R: DATA Transmit/Receive In minimum mode, 8286/8287 transceiver is used for the data bus. DT/ R is used to control the direction of data flow through the transceiver.

 $\mathsf{DEN}$  : Data Enable It is provided as an output enable for the 8286/8287 in a minimum system which uses the transceiver



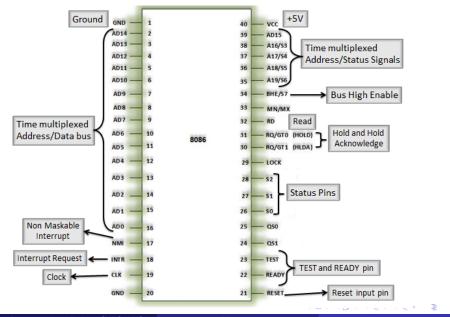
8080 Microprocessor

January 19, 2016 26 / 51

HOLD & HLDA (I/O): Hold and Hold Acknowledge

- Hold indicates that another master is requesting a local bus "HOLD"
- To be acknowledged, HOLD must be active HIGH.
- The processor receiving the "HOLD " request will issue HLDA (HIGH) as an acknowledgement in the middle of the T1-clock cycle.
- With the issue of HLDA, the processor will float the local bus and control lines

# Pins Specific to Maximum mode only



Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

January 19, 2016 28 / 51

# Pin Diagram of 8086

## S2, S1, S0 : Status Pins

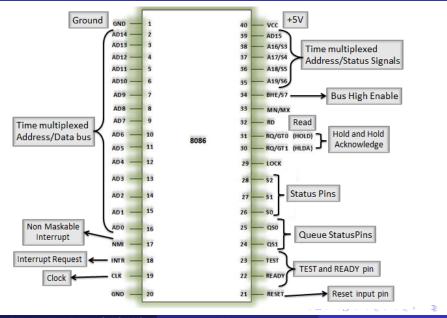
- These pins are active during T4, T1 and T2 states and is returned to passive state 1,1,1 during T3
- Are used by the 8288 bus controller to generate all memory and I/O operation access control signals

S2	S1	S0	Characteristics
0	0	0	Interrupt acknowledge
0	0	1	Read I/O port
0	1	0	Write I/O port
0	1	1	Halt
1	0	0	Code access1 0 1 Read memory
1	1	0	Write memory
1	1	1	Passive State

Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

# Pins Specific to Maximum mode only



Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

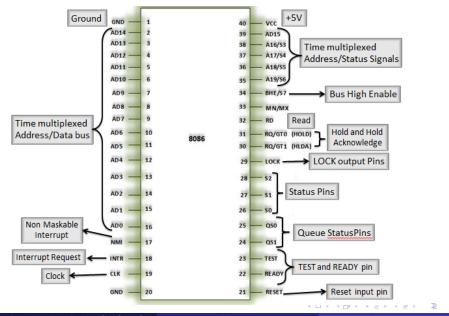
January 19, 2016 30 / 51

#### QS0, QS1: Queue Status

- Queue Status is valid during the clock cycle after which the queue operation is performed
- QS0, QS1 provide status to allow external tracking of the internal 8086 instruction queue

QS1	QS1	Characteristics
0	0	No operation
0	1	First byte of opcode from queue
1	0	Empty the queue
1	1	Subsequent byte from queue

# Pins Specific to Maximum mode only



Richa Upadhyay Prabhu (MPSTME)

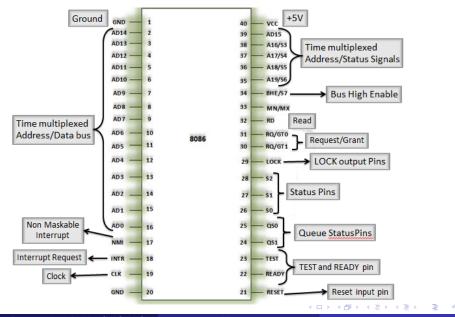
8080 Microprocessor

January 19, 2016 32 / 51

## LOCK

- It indicates to another system bus master, not to gain control of the system bus while LOCK is active Low
- The LOCK signal is activated by the "LOCK" prefix instruction and remains active until the completion of the instruction
- This signal is active Low and floats to tri-state OFF during 'hold acknowledge'

# Pins Specific to Maximum mode only



Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

January 19, 2016 34 / 51

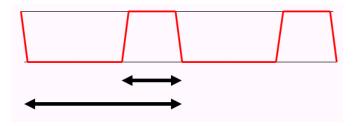
RQ/GT0 and RQ/GT1 (I/O): Request/Grant

- Are used by other processors in a multi processor organization
- Local bus masters of other processors force the processor to release the local bus at the end of the processors current bus cycle
- Each pin is bi-directional and has an internal pull up resistors. Hence they may be left un-connected

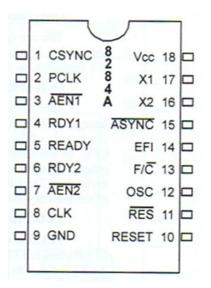
- Ancillary component to the 8086/8088 microprocessors
- The 8284 provides the following basic functions or signals:
  - Clock generation (CLK)
  - RESET synchronization
  - READY synchronization
  - TTL level peripheral clock (PCLK)

The 8088/8086 require a specific waveform for the system clock

- Fast rise and fall times ( i10ns )
- Logic 0: -0.5 to 0.6 V
- Logic 1: 3.9 to 5.0 V
- Duty cycle of 33



#### 33% duty cycle



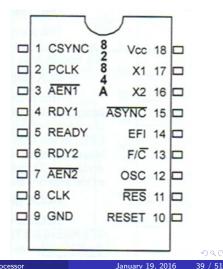
3

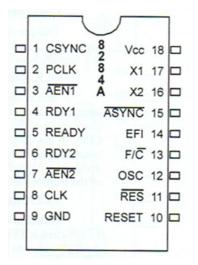
- ∢ ≣ →

-

#### Input Pins

- RES (Reset) In): from power supplier
- X1 and X2 (Crystal In): the crystal frequency must be 3 times the desired frequency for the microprocessor
- RDY1 and AEN1: provide a Ready signal to processor, which will insert a WAIT state to the CPU read/write cycle
- RDY2 and AEN2: For multiprocessor systems





#### **Output Pins**

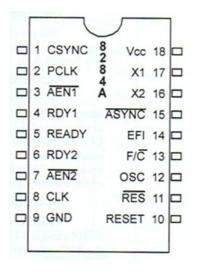
- RESET: reset signal to the 8086/88, activated by RES
- OSC (oscillator): provide to the expansion slot
- CLK (clock): 1/3 of the crystal input, with a duty cycle of 33%
- PCLK: one-half of CLK (1/6 of crystal) with duty cycle of 50% and is TTL compatible.
- READY:

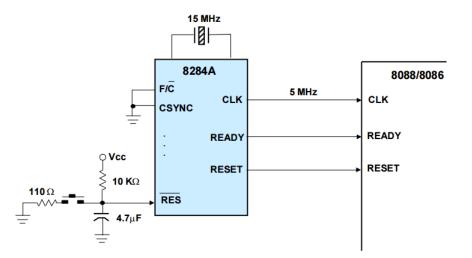
connect to READY input of CPU to insert WAIT state

#### **Output Pins**

- F/C (Frequency/crystal select): If 1, an external clock is provided to the EFI input pin and if 0, an external crystal oscillator connected to X1 and X2 provides the clock
- EFI (External frequency Input): Supplies the timing whenever the F/C is high.
- CSYNC

(Clock Synchronization): Used whenever the EFI input provides synchronization in systems with multiple processors. If the internal crystal oscillator is used,





- < ∃ →

• • • • • • • •

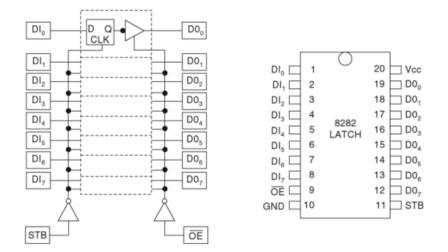
# 8282/8283 LATCH

<br/>

3 🕨 🖌 3

- CMOS octal latching buffer
- provides an eight bit parallel latch/buffer in a 20 pin package
- Basically de-multiplexing the data and addressing bus
- OE (Output Enable) connected to GND, the chip is selected
- STB (Strobe) is connected to the pin ALE (Address Latch Enable) of the processor and takes over the address data from the multiplexed address-/databus

Latches are used to de-multiplex the address/data and address/status lines and commonly have output buffers for driving external loads.



#### Figure: Functional Diagram and Pin Diagram

Richa Upadhyay Prabhu (MPSTME)

Image: A mathematical states and a mathem

э

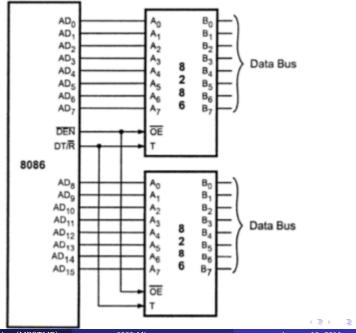
# 8286 TRANSCEIVER

-

Image: A matrix of the second seco

-

- If a system includes several interfaces then to increase current sourcing/sinking capacities it is necessary to use drivers and receivers for data bus also
- Intel 8286 device is used to implement the transceiver block



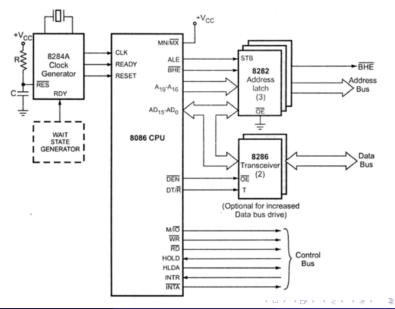
Richa Upadhyay Prabhu (MPSTME)

January 19, 2016 48 / 51

- If a system includes several interfaces then to increase current sourcing/sinking capacities it is necessary to use drivers and receivers for data bus also
- Intel 8286 device is used to implement the transceiver block
- It has 16- tri state elements, 8 receivers and 8 drivers
- That's why TWO 8286 are required to service 16 data lines of 8086
- $\bullet\,$  DT/R is connected to T input, which controls the direction of data flow

- $DT/\overline{R}$  is connected to T input, which controls the direction of data flow
  - $\bullet\,$  When this signal is low, receivers are enabled, so that 8086 can read data from memory and I/O device
  - When this signal goes high, drivers are enabled allowing 8086 to transfer(or write) data into memory and I/O device
- To enable output of transceiver its  $\overline{OE}$  pin should be low, That's why it is connected to DEN pin of 8086.
  - Since  $\overline{DEN}$  signal goes low when CPU is ready to send or receive data

### Basic Minimum mode configuration



Richa Upadhyay Prabhu (MPSTME)

8080 Microprocessor

January 19, 2016 51 / 51

# STRAWBERRY



[] /strawberrydevelopers
[] /strawberry\_app

For more visit:

Strawberrydevelopers.weebly.com