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# 8087 Math Processor

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# Introduction

## Need of Math Processor:

- In application where fast calculation is required
- Also where there is a need to do arithmetic operations on very small and very larger numbers
- 8086 is not designed to do complex mathematical operations
- Highly optimized number crunching programs run slow on general purpose processors

To solve this , special processors with architectures and instruction set optimized for performing complex lengthy calculations.

## 8087 Introduction

- 8087 is referred as Co-processor, as it is used in parallel with the main processor
- Main processor handles general program execution
- 8087 handles specialized math computations
- 8087 can perform computations 10 times faster than 8086

## 8087 Introduction

- 8087 is a processor with its own instruction set
- These instructions are written in program as need interspersed with 8086 instructions
- Each processor decodes all the instructions in the fetched instruction byte stream but executes only its own instruction
- Like 8086, 8087 also has an instruction queue
- While decoding if 8087 finds an 8086 instruction then it simply treats it as NOP.

# DATA TYPES

There are three general type of data types:

- Binary Integer
- Packed decimal
- Real

# Binary Integer Data Type

- Basic format that is used to represent signed binary numbers
- MSB is sign bit; '0' for positive and '1' for negative
- Rest of the bits represent the magnitude of the number
- If number is negative, the magnitude is represented in 2's complement form

# Binary Integer Data Type

Below figures show binary integer format in different lengths for various ranges of numbers

## (a) Word integer (16 Bit Signed Integer)

S	Magnitude
15	0

Sign bit is 0 for positive and 1 for negative.

Range:  $-32768 \leq X \leq +32767$ . Negative number representation in 2's complement form.



# Binary Integer Data Type

Below figures show binary integer format in different lengths for various ranges of numbers

## (b) Short integer (32 Bit Signed Integer)

S	Magnitude
31	0

Range:  $-2 \times 10^9 \leq X \leq 2 \times 10^9$

# Binary Integer Data Type

Below figures show binary integer format in different lengths for various ranges of numbers

## (c) Long Integer (64 Bit Signed Integer)

S	Magnitude
63	0

Range:  $-9 \times 10^{18} \leq X \leq 9 \times 10^{18}$

# Packed Decimal Numbers

- A number is represented as a string of 18 BCD digits
- Each byte of storage can contain two decimal numbers
- MSB bit is sign bit
- format is handy for working with financial programs, e.g. to represent amount as large as \$9,999,999,999,999,999.99
- 8 don't care bits are also there

S	Don't care	Magnitude
79	72	71 0

$-99 \dots 99 \leq X \leq +99 \dots 99$  (18 digits)

# Real Numbers

- Real Numbers or Floating point Numbers, which have both a real and a decimal part
- Basic principle is to use one group of bits to represent the digits and another to represent position of binary point w.r.t. these digits
- Number should be written in scientific notation or it should be normalized
- Process of moving decimal point just to the right of most significant non zero digit is called normalization

For example:  $0.00857 = 8.57 \times 10^{-3}$

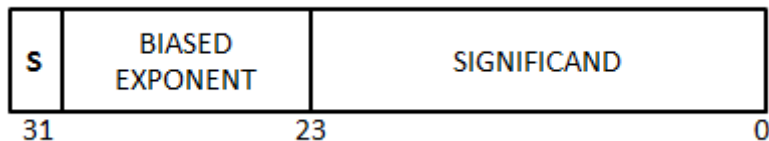
# Real Numbers

For example:  $0.00857 = 8.57 \times 10^{-3}$

- In the example we have the digit part i.e. *significand* or *mantissa*
- And also the exponent part
- Also sign of the exponent, which indicates whether the magnitude is  $> 1$  or  $< 1$

# Real Numbers

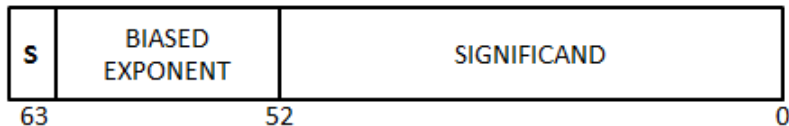
## SHORT REAL



$$1.2 \times 10^{-38} \leq |x| \leq 3.4 \times 10^{38}$$

# Real Numbers

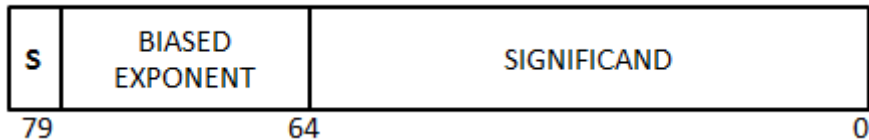
## LONG REAL



$$2.3 \times 10^{-308} \leq |x| \leq 1.7 \times 10^{308}$$

# Real Numbers

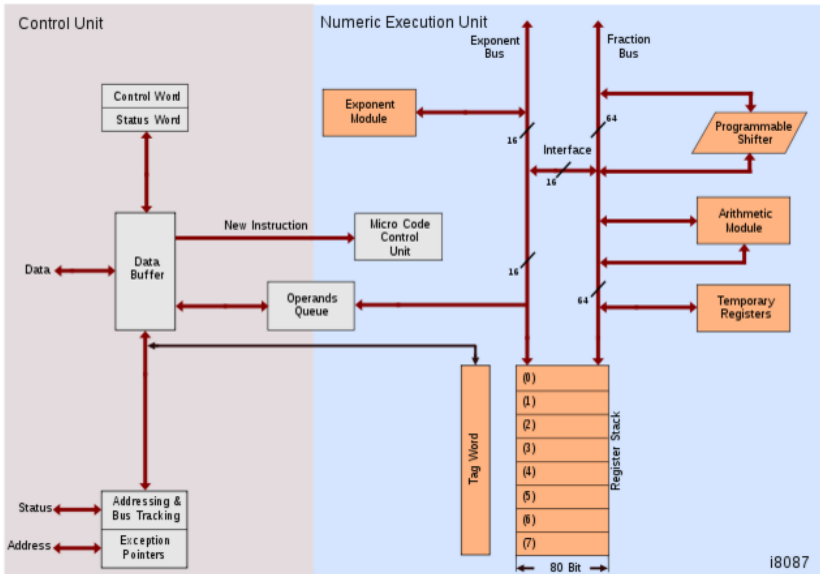
TEMPORARY REAL



$$3.4 \times 10^{-4932} \leq |x| \leq 1.1 \times 10^{4932}$$



# 8087 INTERNAL ARCHITECTURE



# 8087 INTERNAL ARCHITECTURE

The 8087 is divided into 2 sections :

- Control Unit
- Numeric Execution Unit

The **numeric execution unit** executes all numeric processor instructions while **control unit** receives, decodes instructions, read and writes memory operands and executes 8087 control instructions.

These 2 units works asynchronously with each other.

The control unit is majorly responsible for establishing communication between CPU and memory and also for coordinating internal co- processor execution.

# 8087 INTERNAL ARCHITECTURE

## CONTROL UNIT

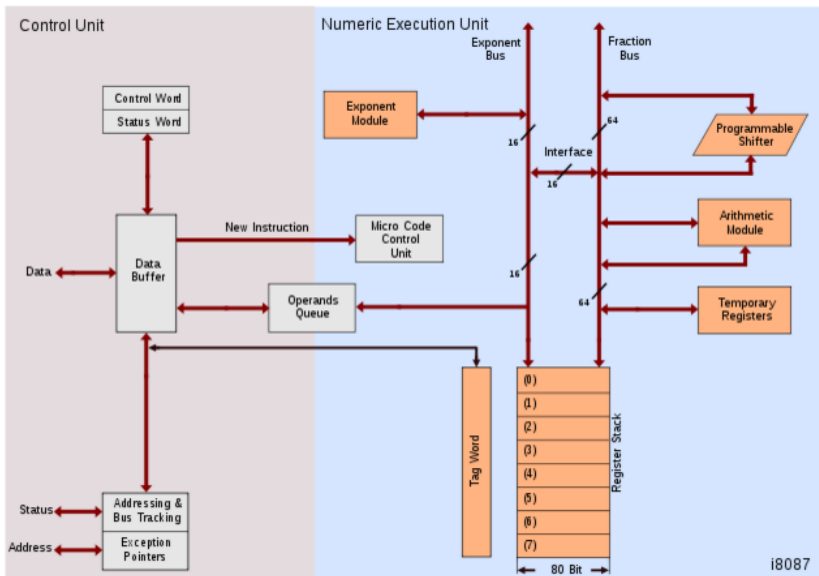
- Used to synchronize the operations between main processor and co-processor
- It receives the instruction opcode, decodes it and reads or write operands from memory
- It continuously monitors data bus to find instruction for 8087
- **Operand Queue:** 8087 maintains a parallel queue similar to the processor, whose length can be adjusted depending on the processor
- For 8086; the queue is of 6 bytes and for 8088 it is of 4 bytes

# 8087 INTERNAL ARCHITECTURE

## CONTROL UNIT

- Queue status input pins  $QS_0$  and  $QS_1$  are used by 8087 to identify instructions fetched by the microprocessor
- 8087 instruction opcodes have 11011 as the most significant bits of first code byte
- Control unit consists of Control word, Status word and Data buffer (will be discussed later)

# 8087 INTERNAL ARCHITECTURE



# 8087 INTERNAL ARCHITECTURE

## NUMERIC EXECUTION UNIT

- Blocks in this unit duplicate the functions performed by control and ALU blocks in microprocessor
- It performs all operations that access and manipulate numeric data in 8087 registers
- Numeric registers are 80 bit wide and the data is routed by 64 bit mantissa/significand bus and a 16 bit sign/exponent bus
- While executing an instruction the NEU pulls up the BUSY signal, which is connected to  $\overline{TEST}$  input of 8086
- CPU is able to distinguish that the execution is not yet completed

# 8087 INTERNAL ARCHITECTURE

**MICROCODE CONTROL UNIT** : generates control signals which are required for execution of instruction

**PROGRAMMABLE SHIFTER** : used for shifting operands during execution of instruction

**DATA BUS INTERFACE**: connects internal data bus of 8087 to main processor data bus

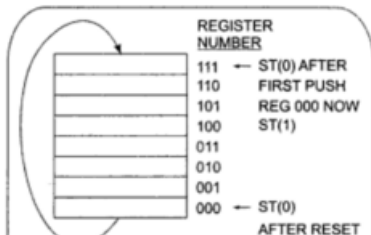
# 8087 INTERNAL ARCHITECTURE

## REGISTER STACK

- 8087 internally works with numbers in 80 bit temporary real format
- To hold these numbers it has a register stack of 80 bits registers, labeled (0)-(7)
- Last in first out stack (same as 8086)
- 8087 has a 3 bit stack pointer, which holds the number of register that is the top of stack

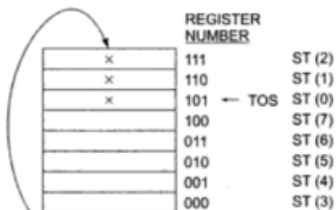


## 8087 INTERNAL ARCHITECTURE



8087 STACK REGISTERS

(a)



8087 STACK REGISTERS

(b)

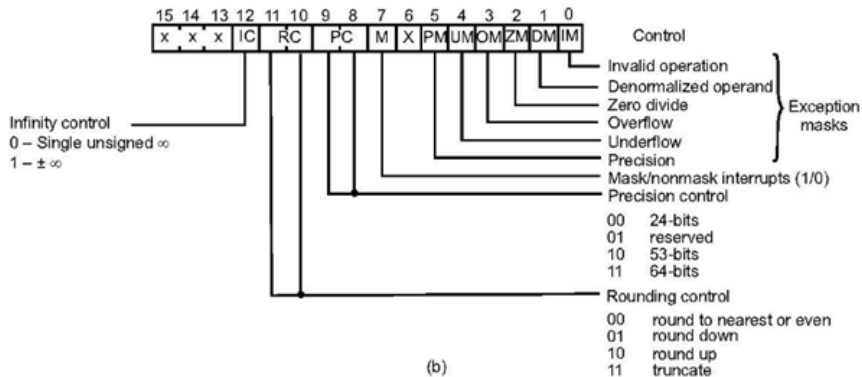
# 8087 INTERNAL ARCHITECTURE

## CONTROL AND STATUS WORD

- Control word is sent to 8087 from 8086, by writing them to a memory location
- 8087 has to execute an instruction which reads the control word from memory
- Status word is sent to 8086 from 8087
- 8087 has to execute an instruction that will write the status word to memory

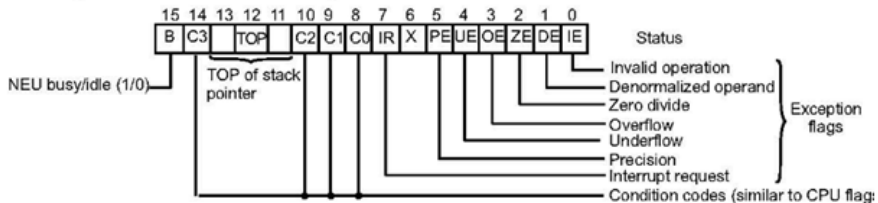
## 8087 INTERNAL ARCHITECTURE

## CONTROL WORD



# 8087 INTERNAL ARCHITECTURE

## STATUS WORD



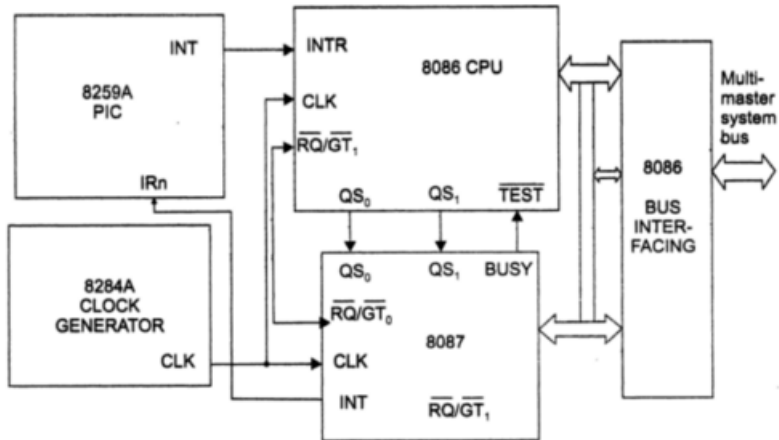
## 8087 Exceptions

- **Invalid operation:** This includes the attempt to calculate the square root of a negative number or say to take out an operand from an empty register
- **Overflow:** Exponent of the result is too large for the destination real format.
- **Zero divide:** Arises when divisor is zero while the dividend is a non-infinite, non-zero number.
- **Denormalized operation:** It arises when an attempt is made to operate on an operand that is yet to be normalized.
- **Under flow:** Exponent of the result is too small to be represented.
- **Precision:** In case the operand is not made to represent in the destination format, causing 8087 to round the result. Also known as In-exact result.

## 8087 operation in case of an exceptions

- 8087 sets the appropriate flag bit in the status word in case of occurrence of any one of the exception conditions.
- The exception mask in the control register is then checked and if the mask bit is set i.e., masked, then a built-in fix-up procedure is followed.
- If the exception is unmasked (i.e., mask bit = 0), then user-written exception handlers take care of such situations.
- This is done by using the INT pin which is normally connected to one of the interrupt input pins of 8259A PIC.


## 8087 and 8086 interfacing



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